

Memory Filter

$$H_{\text{mem}} = 1 / [(K-1) - k \cdot z^{-N}] \rightarrow y_n = (1/K)[x_n + (K-1)y_{n-N}]$$

Sinewave Generator

```
singen(M,N) :=
  for n ∈ 0 .. M - 1
    x_n ← 100 · cos( n · (2 · π / N) )
  return x
```

Zero vector generator

```
zerogen(M,N) :=
  for n ∈ M - 1
    x_n ← 0
  return x
```

$\underline{K} := 15$ Filter time constant

$\underline{N} := 16$ Samples per cycle

$Z_n := (1 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0)^T$ Memory filter - Numerator

$M := 30 \cdot N$ Sample in signal

$Z_d := [K \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ 0 \ (K - 1)]^T$ Memory filter - denominator

Generate input signal

$RZ_d := \text{polyroots}(Z_d)$

$V_{in} := \text{singen}(M, N)$ Sinewave signal

$x_0 := \text{zerogen}\left(\frac{M}{4}, N\right)$ Appended zero value vector

$V_{in} := \text{stack}(V_{in}, x_0)$ Input - Output Array
(required to make vectors equal size)

$NN := \text{rows}(V_{in})$ Size of arrays

$n := 0 .. NN$ Sample array (for plotting)

$$RZ_d = \begin{pmatrix} -0.932 + 0.386i \\ -0.932 - 0.386i \\ -0.386 + 0.932i \\ -0.386 - 0.932i \\ 0.386 - 0.932i \\ 0.386 + 0.932i \\ 0.932 - 0.386i \\ 0.932 + 0.386i \end{pmatrix}$$

Roots on numerator all at zero

Roots of denominator are equally spaced around and inside the unit circle.

Digital Filtering Subroutine

"x" is an array of real numbers containing the input data.

Zn is a vector of coefficients for the filter numerator polynomial in ascending powers of 1/z.

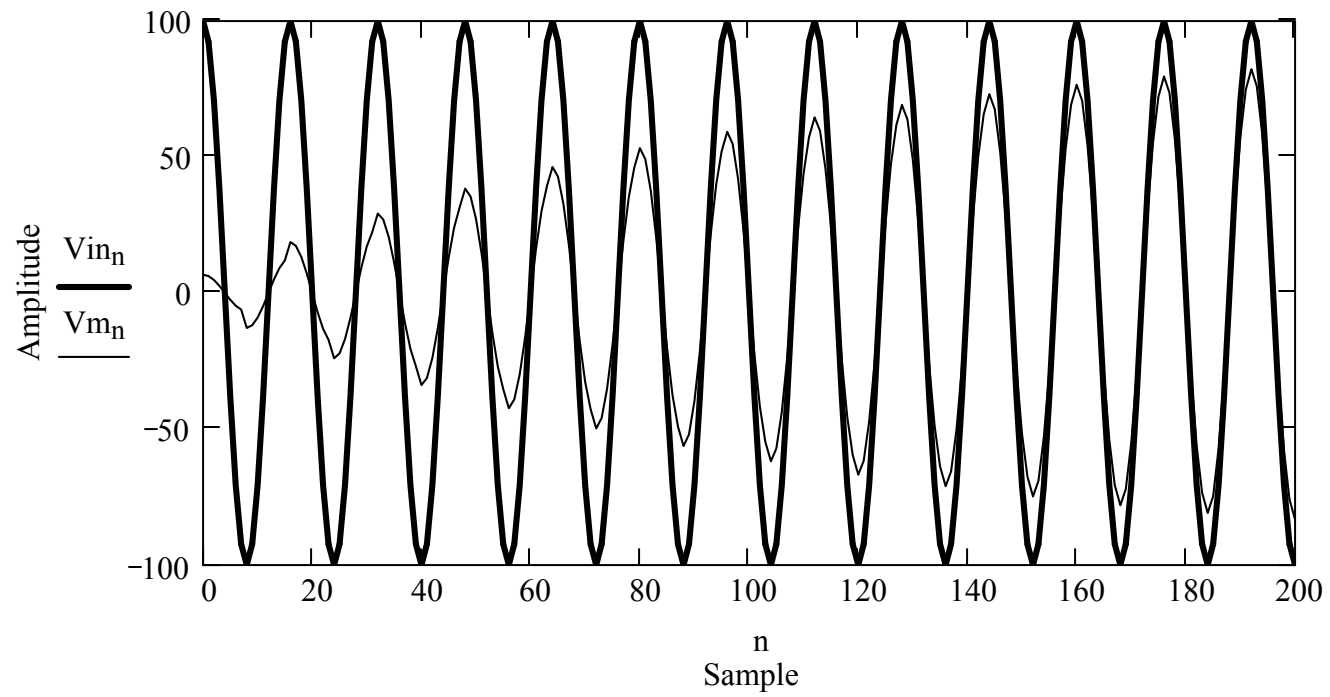
Zd is a vector of coefficients for the filter denominator polynomial in ascending powers of 1/z.

Returned vector is the filtered data.

```
digitalfilter(x ,Zn ,Zd) := | Nd ← rows(Zd)
                             | Nn ← rows(Zn)
                             | Nx ← rows(x)
                             | jn ← 0
                             | jd ← 0
                             | for n ∈ 0 .. Nx - 1
                             |   | yn ← 0
                             |   | z0 ← xn
                             |   | for k ∈ 0 .. jn
                             |   |   | yn ← yn + xn-k · Znk
                             |   |   | for k ∈ 1 .. jd
                             |   |   |   | yn ← yn - Zdk · yn-k if jd > 0
                             |   |   | jn ← jn + 1 if jn < Nn - 1
                             |   |   | jd ← jd + 1 if jd < Nd - 1
                             |   |   | yn ←  $\frac{y_n}{Zd_0}$ 
                             | return y
```

$V_m := \text{digitalfilter}(V_{in}, Z_n, Z_d)$

Transient on startup



Transient on loss of signal

